## FUNCTIONS OF SEVERAL VARIABLES



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As usual, a set of specific values for the inputs always determines a specific value for the output.

Examples:

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$$
\begin{aligned}
& \text { 1. } \text { Area }=\text { Length } \times \text { Width } \\
& \text { 2. } \\
& \text { Perimeter }=2 L+2 W \\
& \text { 3. } A=P\left(1+\frac{r}{n}\right)^{n t}
\end{aligned}
$$

## Examples:

$$
\begin{array}{ll}
\text { 1. } & \text { Area }=\text { Length } \times \text { Width } \\
\text { 2. } & \text { Perimeter }=2 L+2 W \\
\text { 3. } & A=P\left(1+\frac{r}{n}\right)^{n t} \\
\text { 4. } & z=f(x, y)=x^{2}+y^{2}
\end{array}
$$

## A function of several variables may be expressed in several different ways.

## Verbally:

"The output is the sum of the squares of the two inputs."

Algebraically:

$$
z=f(x, y)=x^{2}+y^{2}
$$

Numerically:

| xly | $\mathbf{- 2}$ | $\mathbf{- 1}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{2}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{- 2}$ | 8 | 5 | 4 | 5 | 8 |
| $\mathbf{- 1}$ | 5 | 2 | 1 | 2 | 5 |
| $\mathbf{0}$ | 4 | 1 | 0 | 1 | 4 |
| $\mathbf{1}$ | 5 | 2 | 1 | 2 | 5 |
| $\mathbf{2}$ | 8 | 5 | 4 | 5 | 8 |

## Or Graphically:



## PLOTTING POINTS

We can locate positions in 3-dimensional space by establishing an $x$-axis, $y$-axis, and $z$-axis, and then specifying an $x$-coordinate, $y$-coordinate, and $z$-coordinate for particular points.


$$
(x, y, z)=(4,2,3)
$$

## This orientation called a right-hand coordinate system.



We can use the function below to generate the coordinates of points to plot.

$$
z=f(x, y)=x^{2}+y^{2}
$$

| xly | $\mathbf{- 2}$ | $\mathbf{- 1}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{2}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{- 2}$ | 8 | 5 | 4 | 5 | 8 |
| $\mathbf{- 1}$ | 5 | 2 | 1 | 2 | 5 |
| $\mathbf{0}$ | 4 | 1 | 0 | 1 | 4 |
| $\mathbf{1}$ | 5 | 2 | 1 | 2 | 5 |
| $\mathbf{2}$ | 8 | 5 | 4 | 5 | 8 |

## And from there it's just a matter of plotting points

 until the plot thickens!

## The graph of $\mathrm{z}=0$ is the xy -plane.



The graph of $x=0$ is the $y z-p l a n e$.


The graph of $\mathrm{y}=0$ is the xz -plane.


